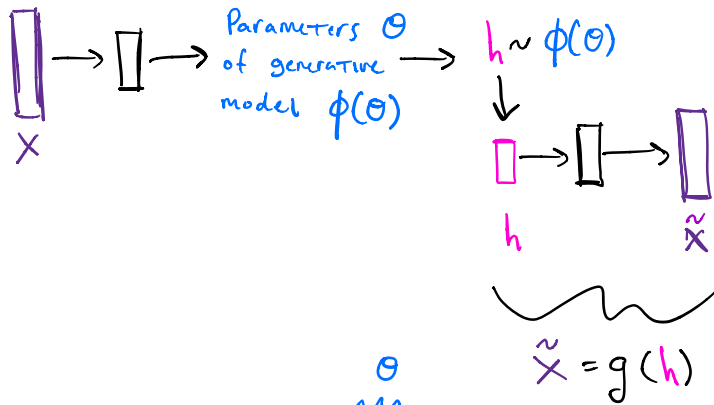
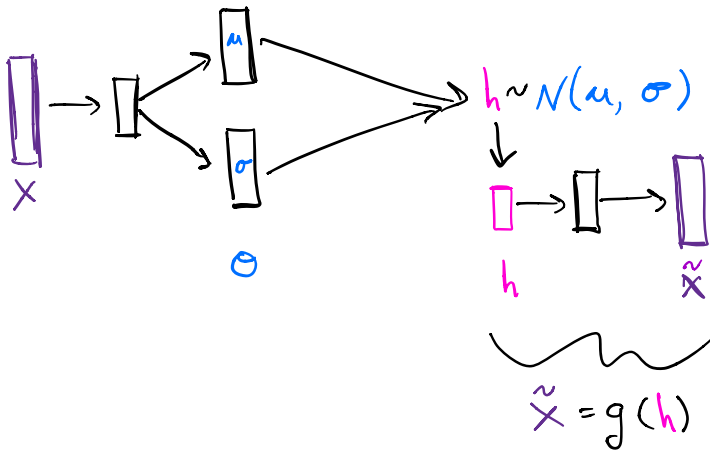


Variational Auto-Encoders (VAEs)



In practice $\phi = \mathcal{N}(\mu, \sigma)$



Note that we predict a vector $\langle 1 \times \text{hidden} \rangle$ of μ and σ , which means we assume dimensions in h are uncorrelated

$$\begin{bmatrix} 5 \\ -3 \\ 0 \end{bmatrix}$$

μ

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & .5 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

σ

So a draw from this
(e.g. via `np.random.normal`)
might be

$$h \approx [4.6, -2.7, 1.3]$$

NOTE That for Normal distributions, we can equivalently
sample $h = \mu + \sigma N(0, I)$ "reparameterization trick"

This is important because we cannot backprop
through a stochastic tensor.

From the auto-diff view, $N(0, I)$ is just a
constant during any particular forward pass

$$e \sim N(0, I)$$

$$h = \underbrace{\mu + \sigma e}$$

Torch cares about these

Let's see some code.