CS3000 Summer 2023 Data Structure Overview

Overview of a few common structures, their basic run-time complexities, and how you might evaluate when and whether they are good choices.

Structure	Find	Insert	Delete, Once Found
Array (unsorted)	O(<i>n</i>)	O(1)	O(<i>n</i>)
Array (sorted)	$O(\lg n)$	O(<i>n</i>)	O(<i>n</i>)
Linked List	O(<i>n</i>)	O(1)	O(1)
Binary Tree	O(<i>n</i>)	O(<i>n</i>)	O(<i>n</i>)
BST (general)	O(<i>h</i>)	O(<i>h</i>)	O(<i>h</i>)
BST (balanced)	$O(\lg n)$	$O(\lg n)$	O(lg <i>n</i>)
Hash Tables	O(1)	O(1)	O(1)

Summary of General Run-Time Complexities

Specialized Structures

Structure	Insert	Remove
Stack	O(1)	O(1)
Queue	O(1)	O(1)
Неар	O(lg <i>n</i>)	O(lg <i>n</i>)

Graphs

Graph Type	Add Vertex	Add Edge	Find Vertex	Find Edge
Adjacency List	O(1) to add to the vertices array	O(1)	O(<i>V</i>])	O(E), if you know which linked list to look in
Adjacency Matrix	O(1) O(V) if we're also concerned with	O(1)	O(<i>V</i>])	O(V), if you've found one vertex and need to see if it's adjacent to another O(1), if you've found

initialized all its relevant edges to the null edge			both vertices and know their positions in the matrix
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Comparison of Usefulness

Choosing the right data structure for the problem you're trying to solve is rarely straightforward. Sometimes a specific data structure is just right for everything you need; for example, if your algorithm needs the data to respect FIFO order, then it should be pretty obviously to use a queue.

However, it is often the case that many different data structures *could* be used Some will just be able to solve the problem more efficiently. So if there are many possibilities open to you, consider what kinds of operations you'll be needing the most. Consider whether your data will be relatively static, or grow and shrink unpredictably. Consider which one is easier to implement and use. All of these factors can come into play.

Structure	Good When	Bad When
Array	You need random access (indexing) to elements by position.	After populating the array once, you do a lot of deletes.
	You know the number of elements you'll need.	You need to search for specific elements.
	You need to sort your data, once, after it's all been inserted (and then you can do binary search).	You don't know the number of elements you'll need, and you end up over-allocating or needing to expand.
Linked List	Your data dynamically grows and shrinks.	You need random access to elements by position.
		You want to do binary search, which doesn't work with Linked Lists.
Stack	You need expression evaluation and syntax parsing.	You're interested in elements with a certain value or position
Queue	You need to respect the order in which data was inserted.	You're interested in elements with a certain value or position
Heaps	You need to have easy access to the min or max $(O(1)$ to find it).	You need your data set completely ordered, not partially ordered.
Binary Search Tree	Your data needs to be sorted, and you do a lot of searches.	Your data might be inserted in an ordered way, making the tree
	You love recursion.	unbalanced. Switch to an AVL tree in this case.

	And pointers.	
Graphs	You have a complex "real world" problem to solve, like finding shortest paths.	Your data lends itself to a parent/child structure.
Hash Tables	You want to use an array, but they're too slow. You want fast access to your data, and you want to be able to delete efficiently.	You need your data to be ordered. Your data + hash function combination result in many collisions.