

CS3000

6/8 - Thurs 11

Admin

- Short HWs due today 9pm
- Long HWs out now, due at 9pm
- Fun recitation today

→ (last long HW)

Agenda

1. All pairs shortest paths
2. Floyd Warshall algorithm
3. Exam #2 logistics, second chance HWs

Recap

Dijkstra's

— restriction on graph type

- directed
- weighted
- non-neg edge weights
- cycles ok

Relax on edge (u, v)

- Can we improve distance to v by going through u ?

Vertex attributes?

- $v.d$ — shortest distance to v from s
- $v.\pi$ — predecessor vertex on shortest path

11. APSP

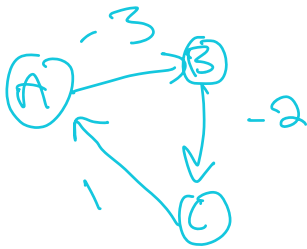
SSSP \rightarrow APSP
(Dijkstra's) (Floyd Warshall)

• for every pair of vertices u and v ,
find shortest path from u to v

- directed
- weighted
- negative weights ok!
- cycles ok!

negative weight
cycles not
ok

(ex) negative weight cycles bad in **SP**



SP from A to B...

A \rightarrow B -3

A \rightarrow B \rightarrow C \rightarrow A \rightarrow B -7

\rightarrow C \rightarrow A \rightarrow B -11

SSSP \sim BFS, Dijkstra's

$v.d$

$v.\pi$

\rightarrow shortest path from s to v

For every vertex, care about one path

now... APSP

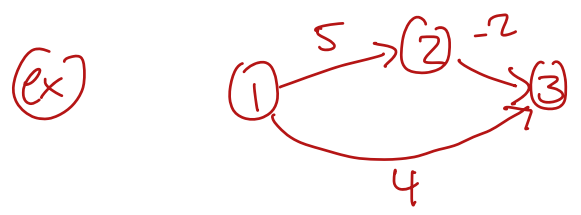
For every vertex, we care about $|V|$ paths

- care about $v.d$ from A

v.d from B
 v.d from C
 ⋮
 v.d from all vertices

- care about v.π from A
 v.π from B
 ⋮
 v.π from all vertices

Represent d, π values in a table
 - graph G stored in adj matrix



D table $V \times V$

| | 1 | 2 | 3 |
|---|----------|----------|----|
| 1 | 0 | 5 | 3 |
| 2 | ∞ | 0 | -2 |
| 3 | ∞ | ∞ | 0 |

Goal

π table $V \times V$

| | 1 | 2 | 3 |
|---|-----|-----|-----|
| 1 | nil | 1 | 2 |
| 2 | nil | nil | 2 |
| 3 | nil | nil | nil |

APSP is an optimization problem

- use Dynamic Programming! ↓
- Build D tables, π tables

- update based on previous values

- How can we use solutions to smaller problems to solve the bigger problem?

recursive formula



fill in tables bottom up

Build many D tables

- $D^{(k)}$ is the k^{th} D table

- has entry for every pair of vertices

- $d_{ij}^{(k)} \rightarrow$ one entry in k^{th} D table

\rightarrow distance a from i to j (so far...)

$\pi^{(k)}$ is k^{th} π table

$D^{(0)}$ table (base case)

- don't know paths yet

- only edges so far

$$d_{ij}^{(0)} = \begin{cases} 0 & \text{if } i=j \\ \infty & \text{if } i \neq j \text{ and no edge } (i,j) \\ w(i,j) & \text{otherwise} \end{cases}$$

$\pi^{(0)}$ table (base case)

- if (i,j) exists, $\pi_{ij}^{(0)} = i$

Starting from $D^{(0)}$, want to fix:

- there might be a shorter path $i \rightsquigarrow j$ that doesn't go through (i,j)
- there might be a path $i \rightsquigarrow j$ even if (i,j) does not exist

2. Floyd Warshall

- just D tables
- when we build $D^{(k)}$, we try to improve $d_{ij}^{(k-1)}$
- does it help to go through vertex (k) ?

$i \rightsquigarrow j$ vs. $i \rightsquigarrow k \rightsquigarrow j$

$\rightsquigarrow = \text{path}$

Recursive Formula \rightarrow Bottom-up code

$$d_{ij}^{(k)} = \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$$

Is it better to go through k ?

FLOYD-WARSHALL(G, w)

```

1 let  $D^{(0)}$  be a new  $V \times V$  matrix
2 for  $i = 1$  to  $V$ 
3   for  $j = 1$  to  $V$ 
4     if  $i == j$ 
5        $d_{ij}^{(0)} = 0$ 
6     elseif  $(i, j) \in G.E$ 
7        $d_{ij}^{(0)} = w(i, j)$ 
8     else
9        $d_{ij}^{(0)} = \infty$ 
10  for  $k = 1$  to  $V$ 
11    let  $D^{(k)}$  be a new  $V \times V$  matrix
12    for  $i = 1$  to  $V$ 
13      for  $j = 1$  to  $V$ 
14         $d_{ij}^{(k)} = \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$ 
15  return  $D^{(V)}$ 

```

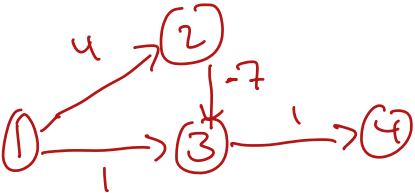
$D^{(0)}$

Recursive formula,
implemented bottom-up

$\Theta(V^3)$

10:48

Floyd-Warshall example



$D^{(0)}$ (just edges)

| | 1 | 2 | 3 | 4 |
|---|----------|----------|----------|----------|
| 1 | 0 | 4 | 1 | ∞ |
| 2 | ∞ | 0 | -7 | ∞ |
| 3 | ∞ | ∞ | 0 | 1 |
| 4 | ∞ | ∞ | ∞ | 0 |

$D^{(1)}$



Can we do better
by going through 1?

$d_{ij}^{(0)}$ vs. $d_{i1}^{(0)} + d_{1j}^{(0)}$
 ∞ vs. ∞

$D^{(1)} = D^{(0)}$
no thing changes!

$D^{(2)}$



go through 2?

yes!

$1 \rightarrow 3$

$1 \rightarrow 2 \rightarrow 3$

$D^{(2)}$

| | 1 | 2 | 3 | 4 |
|---|----------|----------|----------|----------|
| 1 | 0 | 4 | -3 | ∞ |
| 2 | ∞ | 0 | -7 | ∞ |
| 3 | ∞ | ∞ | 0 | 1 |
| 4 | ∞ | ∞ | ∞ | 0 |



$d_{ij}^{(1)}$ vs. $d_{i2}^{(1)} + d_{2j}^{(1)}$

$D^{(3)}$



can we go through (3)

yes!

$1 \rightarrow 3 \rightarrow 4$

$2 \rightarrow 3 \rightarrow 4$

$D^{(3)}$

| | 1 | 2 | 3 | 4 |
|---|----------|----------|----------|----|
| 1 | 0 | 4 | -3 | -2 |
| 2 | ∞ | 0 | -7 | -6 |
| 3 | ∞ | ∞ | 0 | 1 |
| 4 | ∞ | ∞ | ∞ | 0 |



$d_{ij}^{(2)}$ vs. $d_{i3}^{(2)} + d_{3j}^{(2)}$

distances

$D^{(4)}$



can we go through (4)?

no!

here!
 $D^{(4)} = D^{(3)} = \text{final table}$

3. Exam + Second Chzncu Hw

• exam #2 } 6/15 during class

- on paper
- 8.5 x 11 in cheat sheet, one side
- 90-min exam

• Topics

- greedy
- heap sort
- MST
- max flow
- amortized
- BFS
- Dijkstra (SSSP)
- DFS
- topo
- A* / SP

• Practice

- problems out Sat
- solutions out mon/tues.

↳ go through in recitation

• Types of Questions

- what would greedy choice be?
 - argue it's optimal
 - write pseudo code
 - which greedy choice is better?
- } greedy

- ~~alg~~ what does heapsort do?
- alg. analysis on sequence of n operations
- vs. worst case

Graph Questions

- what does this do on this graph?
- modify known algo to work on a different type of graph
or
produce a different output
- utility code in the exam
- write pseudocode to do something new
- run time of a given algorithm

Second chance HWS

- one long } resubmit for new grade
 - one short } (except short 4)
- ↳ sep. on gradescope
- update original submission grade

Deadline
6/20 9pm

no late submissions