

Admin

- HW5 due 6/12 9pm
 - ↳ Submit on time if want for 2nd chance
- APP8 due 11:30AM tmw
- practice for exam 2
 - ↳ Sols out tmw
 - review in 6/10 recitation
- XC exam 8 on 6/10

I. SSSP

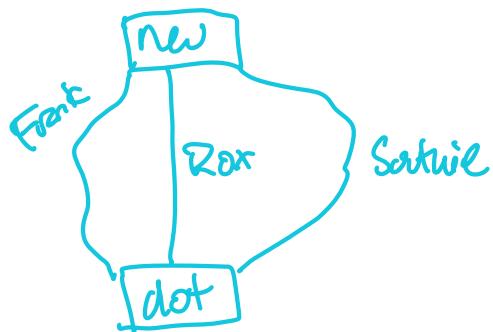
↳ from 2 starting vertices
 shortest path \rightarrow to every reachable vertex
 shortest path $s \rightsquigarrow v$ is a path
 from s to v with least total weight

So far...

- BFS: shortest path : # edges on the path \nearrow
 undirected, unweighted
 - DFS: all reachable vertices
 directed, unweighted
 topo sort, cycle detection
 - MST: least total weight for a
 spanning tree (subset of E , \nearrow
 \approx n)
- Undirected, weighted
- today's graphs:

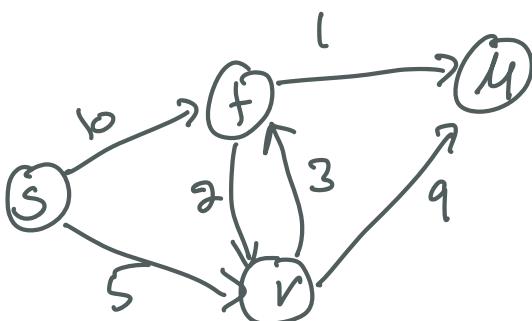
 - directed
 - weighted
- optimization

today's approach



- optimize: overall weight (not # edges)
- IRL: weights represent time, distance

(*) ∞



valid path from s to t

$$s, t \quad w = 10$$

$$s, v, t \quad w = 5 + 3 = 8$$

$$s, v, t, v, t \quad w = 13$$

optimizing for shortest path

SSSP

Dijkstra
Bellman-Ford

needed for Dijkstra's:

- weighted
- cycles OK!
- non negative weights
- directed?

2. Dijkstra's overview

↳ greedy soln for SSSP

• like Prim's - start with path to every vertex

as we explore it

(but)! path might get updated

if we can get to the vertex another way

vertex attributes:

$v.d$ = distance from $S \rightarrow v$

$v.\pi$ = predecessor on shorter path

Algo: $\text{DIJKSTRA}(G, w, s)$

Graph
adj list weight
 $w(u, v)$ starting vertex

First guess:



best way to get to s 's
neighbors is directly from s

initialize:

$$v.d = \infty \quad S.d = 0$$

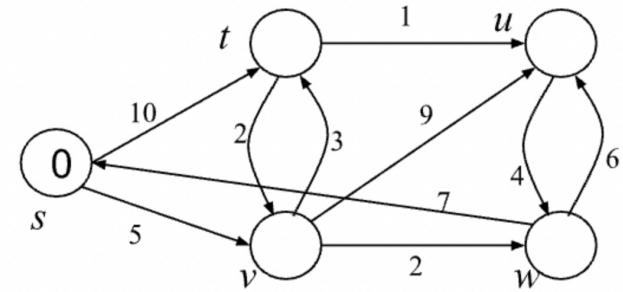
$$v.\pi = \text{nil} \quad S.\pi = \text{nil}$$

Relaxing

Explore other vertices,
possibly update path/distance

RELAX(u, v, w) \rightarrow is it better to get to v by going through u ? Also needed:

if $u.d + w(u,v) < v.d$	Heap H	Set A
$v.d = u.d + w(u,v)$	• vertices to proc	• vertices in proc or done
$v.\pi = u$	• keyed on $v.d$	• $v.d$ is final!



<u>H</u>	<u>Extracted</u>	<u>A</u>	<u>vertex updates</u>
s, t, v, u, w	s	$\{s\}$	$t.d = 10$
t, v, u, w	v	$\{s, v\}$	$v.d = 5$
t, u, w	w	$\{s, v, w\}$	$t.\pi, v.\pi = s$
t, u	$+$	$\{s, v, w, t\}$	$t.d = 8$
u	u	$\{s, v, w, t, u\}$	$w.d = 7$

3. Dijkstra's Proof

\hookrightarrow value of optimal solution
(distance values)

Goal: $\forall v \in V \cdot v.d = \delta(s, v)$ for all $v \in V$

$\delta(s, v)$ distance of actual shortest path from s to v
 $v.d$ distance value produced by the algorithm

Agree on:

$$\text{(H1)} \quad v.d \geq \delta(s, v)$$

- if $v.d$ is wrong, it's worse and not better than optimal

#2 actual shortest path $s \rightsquigarrow v$ (u, v) is edge in the path

$$s \rightsquigarrow u \rightarrow v$$

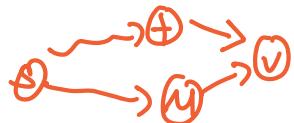
If $u.d = \delta(s, u)$, then $v.d = \delta(s, v)$

after RELAX edge (u, v)

now... proof by induction on $|A|$

- vertex x is added to A ,
distance value is finalized
- before adding to A vertex
 x is removed from heap H

what if ...



but this
is a real
S.P.!

Base case

$|A|=1$ when $|A|=1$, the only vertex
in it is s . $s.d=0$

$$\delta(s, s) = 0$$



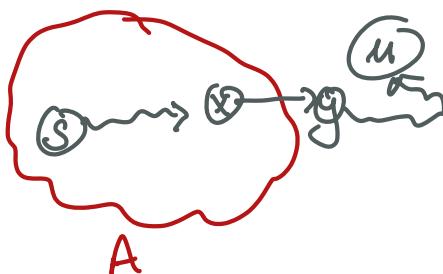
$v.d = \delta(s, v)$ for every $v \in A$
up to $|A|=k$

↳ now we add vertex u , the
 $k+1^{\text{th}}$ vertex into A

- $u.d$ is final
- $u.d$ was smallest in heap
- at same point, we relaxed (x, y)

↳ by IH, $x.d = \delta(s, x)$

by #2, relaxing (x, y) gives us $y.d = \delta(s, y)$



actual S.P.
from s to u
 y precedes u
on S.P.
edge (x, y)
 x is in A

Everything we know!

$x.d = \delta(s, x)$ by IH

$\delta(s, y) \leq \delta(s, u)$ b/c y precedes u
non-neg edge weights

$u.d \leq y.d$ b/c u was extracted first

$u.d \geq \delta(s, u)$ by #1

$y.d = \delta(s, y)$ by #2

String inequalities together

$$\delta(s, y) \leq \delta(s, u) \leq u.d \leq y.d$$

but! $\delta(s, y) = y.d$

so...

$$\delta(s, y) = \delta(s, u) = u.d = y.d$$

$\rightarrow u.d = \delta(s, u) !!! \star$

