C53810 DAY 6 FED 4 - MATRIX - MATRIX MULTIPLICATION - LINEAR COMBINATIONS

-> MATRIX MULTIPLICATION AS A FUNCTION (TRANSFORMATION)

-> BUILDING MATRIX FUNCTION FROM LINEARITY

-> SCALING

- ROTATING - Composing MATRIX Functions BAX = Y MATRIX-MATRIX MULTIPLICATION: SHAPE RULE - N RONS N RONS N RONS LET A MAS SHAPE NOXMA

B WAS SHAPE NOXMB MARRIX MULTIPLICATION ONLY DEFINED WHEN Ma= Nb AB, WHEN DEFINED, HAS SHAPE NOXMB

A HAS SHADE 10 x 17
B HAS SHADE 17 x 14 SHAPE PULE EXAMPLE GIVE OUTPUT SHAPE OF EACH OPERATION BA (10×17)(17×14) (10×14)

TRANSPOSE OF A MATRIX SWAPS ROOS (COLS)
$$A = \begin{bmatrix} 1 & 3 & 3 \\ -1 & 5 & 6 \end{bmatrix}$$

$$A^{T} = \begin{bmatrix} 1 & 4 \\ 3 & 5 \end{bmatrix}$$

$$X = \begin{bmatrix} 1 & 3 & 3 \\ 3 & 6 \end{bmatrix}$$

$$X = \begin{bmatrix} 1 & 3 & 3 \\ 3 & 6 \end{bmatrix}$$

ICA I GIVE SMADE OF EACH MATRIX PRODUCT

IF IT EXISTS

SMADE (A) =
$$3 \times 3$$
 SMADE (b) = 3×1

SMADE (C) = 3×4 SMADE (D) = 1×4

AB CA AC DCTB

(3x3)(3x1) (3x4)(3x3) (3x3)(3x4) (m4)(4x3)(3x1)

(3x1) NOT (3x4) (3x4) (1x3)(3x1)

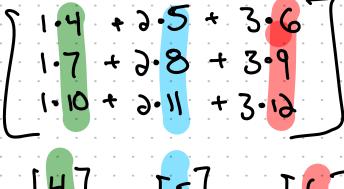
DEFINED

MATRIX - MATRIX MULTIPLICATION: COMPUTING (DOT PRODUCT) (3×2) (3×3) (3×3) 1.3 +0.-2=3

EACH ELEMENT IN PRODUCT MATRIX IS DOT PRODUCT OF CORRESPONDING ROW (LEFT MATRIX)

LINEAR COMBINATION (WEIGHTED SOM) A LINEAR COMBINATION OF XO, XI, X&, ... 15 00 X0 + 0, X1 + d2 X2+...

WHERE EACH XI ARE SCALARS



3×3
ector multiplication
combination
lumns of the matrix

= (-)

4

7

+ 3

9

ICA 1.5 BUILD THE MATRIX A WHICH, WHEN

MULTIPLIED AS AX, ALWAYS VIELDS

THE SAME VELTOR X

$$A = \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} d_0 & a_1 \\ x_1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$$

WHAT 15 A? = $X_0 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + X_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$

15 A LINEAR COMBO OF ROWS OF A

TRANSPOSE IDENTITIES AND HOW THEY RELATE MATRIX-VECTOR TO VECTOR-MATRIX MULTIPLICATIONS $\left(A^{\tau}\right)^{T} = A \qquad \left(xA\right)^{T} = A^{T}x^{T}$ $(AB)^T = B^TA^T \qquad (A\times)^T = x^TA^T$

MATRIX-VELTOR AND VELTOR MATRIX MULTIPLICATIONS

ARE A THANSPOSE AWAY FROM EACH OTHER

CONVENTION;

PREFER MATRIX-VELTOR MULTIPLICATION WHERE
POSSIBLE (COL VELTORS)

(Avoid VECTOR-MATRIX W) ROW VECTORS)

IN GENERAL 17 15 NOT ALWAYS TRUE

THAT AB = BA

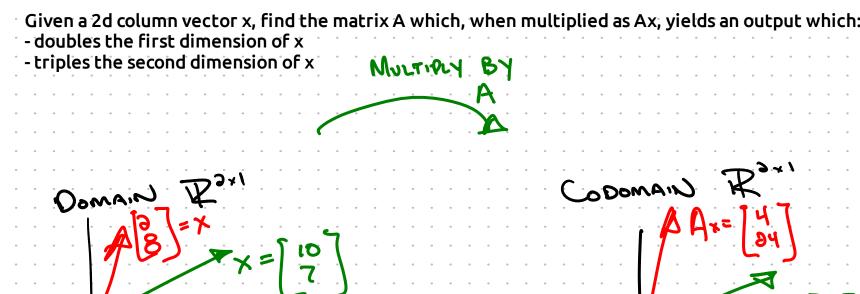
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MATRIX MULTIPLICATION 1)
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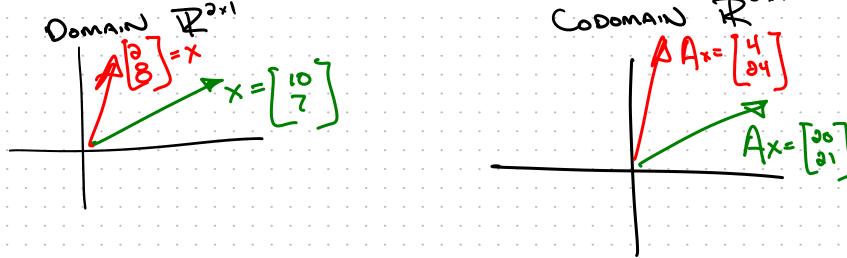
$$\begin{bmatrix} 1 & 3 & 3 & 3 \\ 1 & 3 & 3 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 3 \end{bmatrix}$$

1-1-3-3-3

LET AER CONSIDER F. ROLL - ROLL

$$f(x) = Ax = b$$





$$(9*1)$$

$$(9*1)$$

$$(9*1)$$

$$(9*1)$$

 $A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 \end{bmatrix}$

$$X = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

LET
$$X = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} + O \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
LET WANT A WITH TILITED TITLED.

$$X = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

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$$X = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} a_0 a_1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} a_0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} a_1 \\ 0 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} a_0 a_1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} a_0 \\ 0 \end{bmatrix} + \begin{bmatrix} a_1 \\ 0 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} a_0 a_1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} a_0 \\ 0 \end{bmatrix} + \begin{bmatrix} a_1 \\ 0 \end{bmatrix}$$

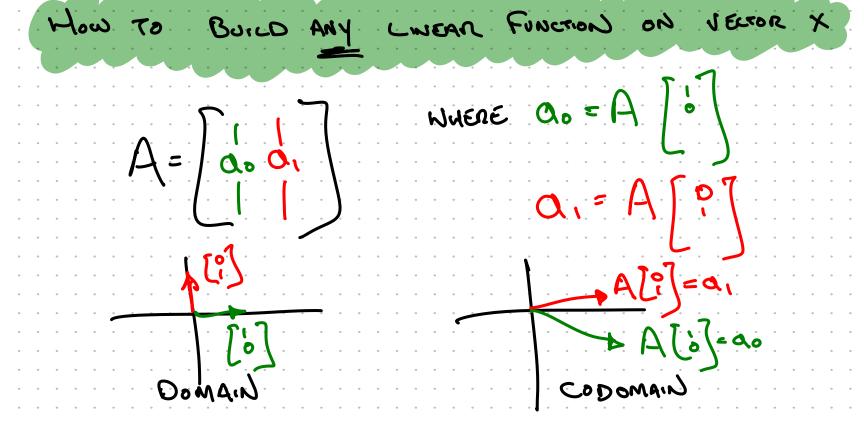
BUT YOU JUST BUILT A FROM ONLY TWO INPUT
VECTORS, HOW BO YOU KNOW IT WORKS FOR OTHERS?

MARRIX MULTIPLICATION (BY A) IS CONEAR
$$A(\alpha x + \beta y) = \alpha A x + \beta A y$$

$$Y = \begin{bmatrix} 77 \\ -8 \end{bmatrix} \in A \in A = \begin{bmatrix} 147 \\ -6 \end{bmatrix} = 7 A \begin{bmatrix} 6 \\ -6 \end{bmatrix} - 3 A \begin{bmatrix} 7 \\ 6 \end{bmatrix} = 7 A \begin{bmatrix} 6 \\ 6 \end{bmatrix} - 3 A \begin{bmatrix} 7 \\ 6 \end{bmatrix} = 7 \begin{bmatrix} 6 \\ 6 \end{bmatrix} - 3 \begin{bmatrix} 6 \\ 6 \end{bmatrix} = 7 \begin{bmatrix} 6 \\ 6 \end{bmatrix} - 3 \begin{bmatrix} 6 \\ 6 \end{bmatrix} = \begin{bmatrix} 147 \\ -6 \end{bmatrix}$$

BUT YOU JUST BUILT A FROM ONLY TWO INPUT

$$\begin{bmatrix} 14 \\ -6 \end{bmatrix} = 3 \begin{bmatrix} -7 \\ -3 \end{bmatrix}$$



ROTATION ABOUT ORIGIN
IS A LINEAR TRANSFORM

$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

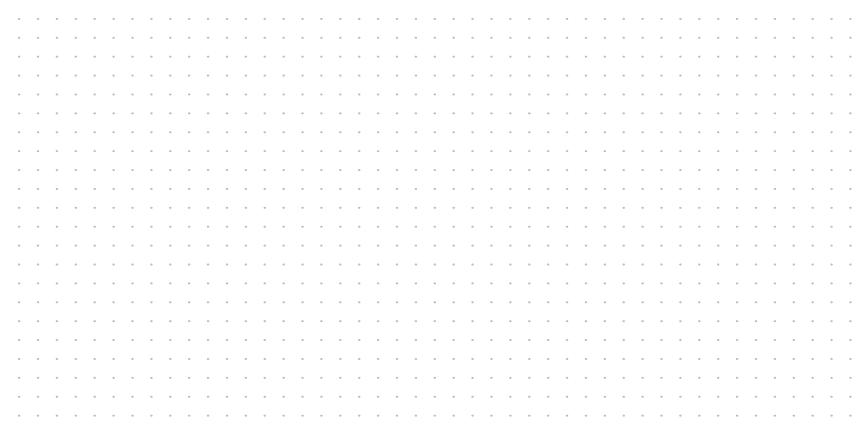
$$\begin{bmatrix}
c_0 c_0 c_0 \\
c_0 c_1 c_0
\end{bmatrix}
\begin{bmatrix}
x_0 \\
x_1 \\
x_2
\end{bmatrix} = c_0 \begin{bmatrix}
0 \\
0
\end{bmatrix}
\begin{bmatrix}
x_0 \\
x_1
\end{bmatrix}$$

$$+ c_0 \begin{bmatrix}
0 \\
0
\end{bmatrix}
\begin{bmatrix}
x_1 \\
0
\end{bmatrix}
\begin{bmatrix}
x_1 \\
0
\end{bmatrix}$$

.

$$A = C \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

BAX=B-X



Composing Functions

$$ABx = A(Bx)$$

FIRST APPLY TRANSFORM B TO X

THEN APPLY TRANSFORM A TO X

 $\begin{cases} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

BAX

