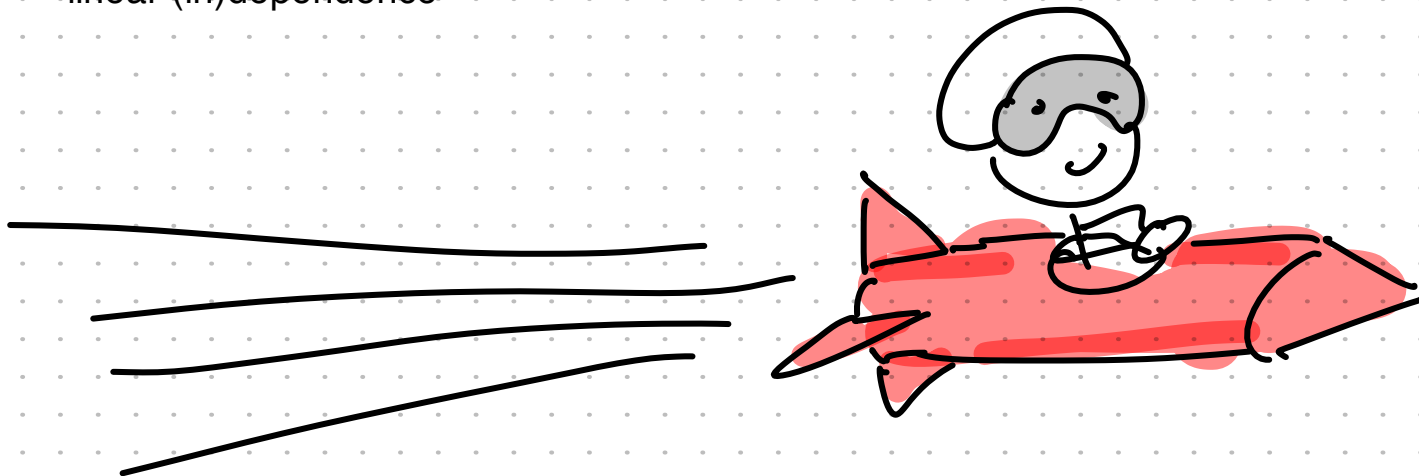


CS 2810 Day 7
Feb 8 2022

Admin: ICA in notes

Describing a set of vectors:

- span
- linear (in)dependence



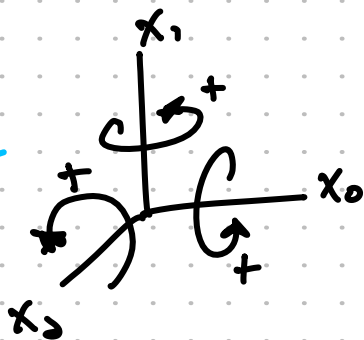
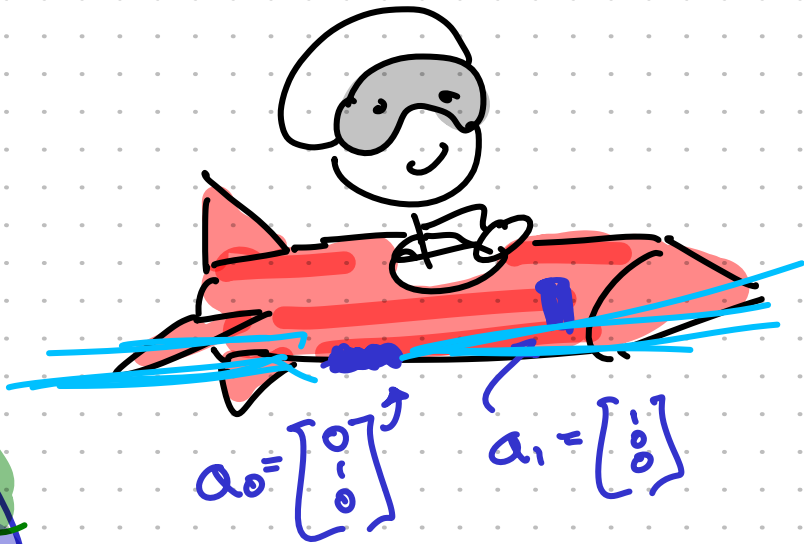
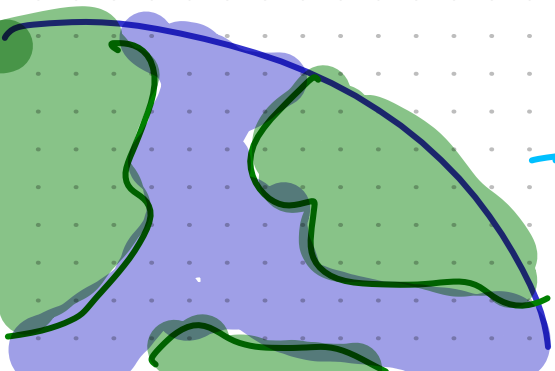
An astronaut is spinning in outer space and needs to stop before they get dizzy! Their spaceship needs impulse $b = [10, -11, 0]^T$ to stop rotating, what control signals x_0, x_1 should they use with their boosters a_0, a_1, \dots to stop?

$$b = \begin{bmatrix} 10 \\ -11 \\ 0 \end{bmatrix}$$

$$x_0 = -10$$

$$-10 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -10 \end{bmatrix}$$

$$x_1 a_1 = 10 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 10 \\ 0 \end{bmatrix}$$



$$\begin{bmatrix} N & N & N \\ N & N & N \end{bmatrix} = x_0 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + x_1 \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$$

$$\left[\begin{array}{c|c} 0 & 0 \\ 0 & 0 \end{array} \right] \begin{array}{c} N \\ N \\ N \end{array}$$

ICA 1: An astronaut is spinning in outer space and needs to stop before they get dizzy! Their spaceship needs impulse $\vec{b} = [b_0, b_1, b_2]$ to stop rotating.

- Is there always a control signal x_0, x_1 which produces the needed impulse, for any \vec{b} ?
 - If not, which impulses, b , can be generated from boosters a_0, a_1 ?
 - What boosters would you need to add to ensure that the rocket can produce any impulse?
- No! if $b_2 = 0$, then b cannot be written as a linear combo of a_0, a_1
- all the b where $b_2=0$ (can be any value in b_0 and b_1)

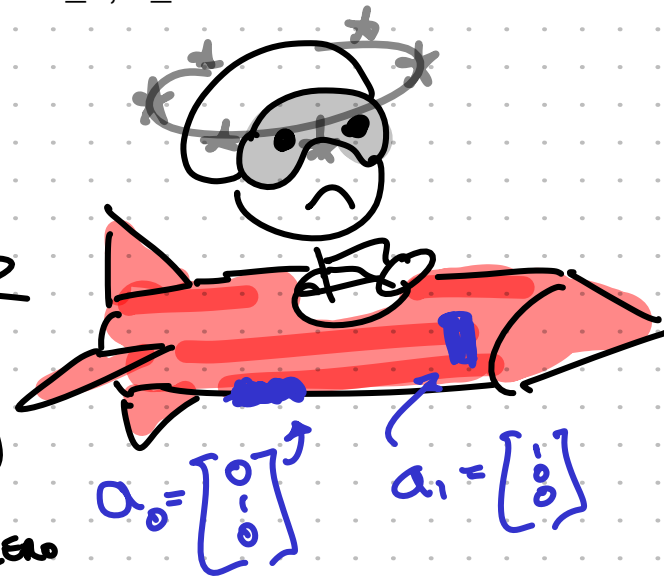
$$\vec{b} = x_0 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

for some $x_0, x_1 \in \mathbb{R}$

$$a_0 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$a_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Non zero



Span [and its rocket ship connection]

The span of a set of vectors a_0, a_1, a_2, \dots is the set of all vectors which can be written as a linear combination

$$\text{SPAN}(\vec{a}_0, \vec{a}_1, \vec{a}_2) = \{x_0\vec{a}_0 + x_1\vec{a}_1 + \dots \mid x_i \in \mathbb{R}\}$$

[The span of boosters a_0, a_1, a_2 are all the impulses that they could possibly create]

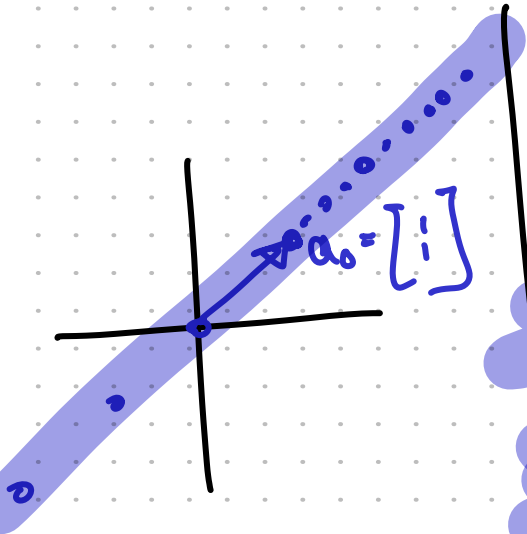
$$a_0 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \text{is} \quad \begin{bmatrix} 11 \\ 11 \\ 0 \end{bmatrix} \quad \text{in} \quad \text{SPAN}(a_0)?$$

ICA 2

MAKE THE SPAN OF EACH SET OF VECTORS

$$x_0 a_0 + x_1 a_1 = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 3 & 0 & 2 \\ 0 & -2 & 4 \end{array} \right]$$



$$a_1 = \begin{bmatrix} 0 \\ -2 \end{bmatrix}$$

$$a_0 = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$a_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$a_2 = \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$

$$a_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

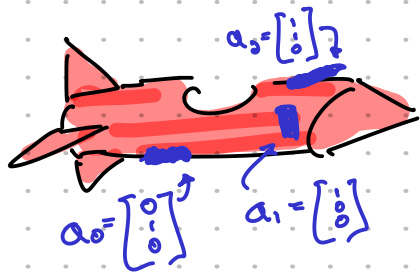
ICA 3: Which of the rockets below is capable of producing any rotation $\vec{b} = [b_0, b_1, b_2]^T$ while costing the least amount of money?

What conditions must a_0, a_1, a_2, \dots meet so that the rocket can produce any rotation?

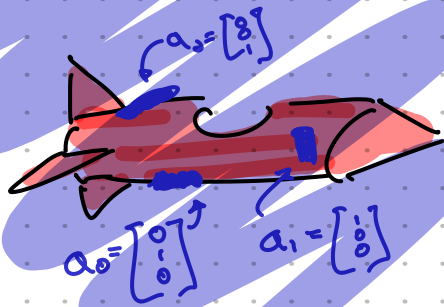
$$\text{SPAN}(a_0, a_1, a_2) = \mathbb{R}^3$$

Its possible to produce every b
from linear combinations of a

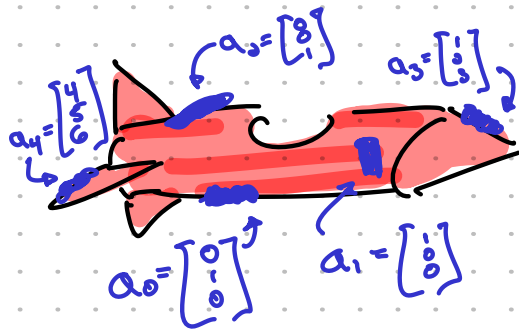
ROCKET A (\$3)



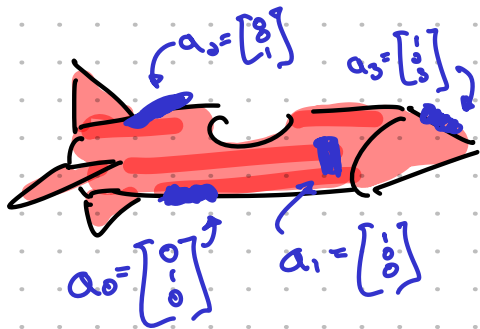
ROCKET B (\$3)



ROCKET C (\$5)



ROCKET C (\$5)



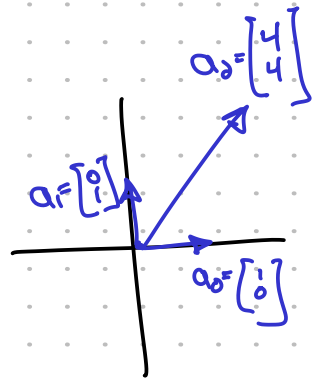
$$a_3 = 1 \cdot a_1 + 2a_0 + 3a_2$$

Linear independence (definition 1 of 2)

We say that a set of vectors a_0, a_1, a_2, \dots is linearly dependent if some vector can be written as a linear combination of the others:

$$\text{THERE EXISTS } x_i \in \mathbb{R} \text{ WITH } a_0 = x_1 a_1 + x_2 a_2 + \dots$$

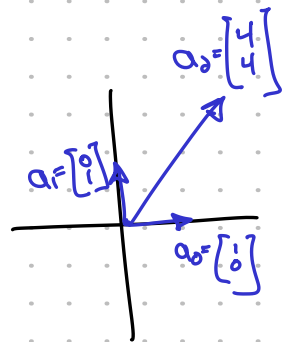
[Linearly dependent boosters are wasteful ... they produce an impulse which could've been created by the other boosters]



Linear independence (definition 2 of 2)

We say that a set of vectors a_0, a_1, a_2, \dots is linearly dependent if there exists some scalars x_0, x_1, \dots (not all equal to zero) with:

$$\vec{0} = x_0 \vec{a}_0 + x_1 \vec{a}_1 + \dots$$



TESTING FOR LINEAR DEPENDENCE

ARE $\begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}$ LINEARLY DEPENDENT?

GOAL: FIND ALL x_0, x_1, x_2 WITH

$$\vec{0} = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix} x_0 + \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} x_1 + \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} x_2$$

IF ANY NON ZERO SOLUTIONS EXIST \rightarrow LINEAR DEPENDENCE

TESTING FOR LINEAR DEPENDENCE

GOAL: FIND ALL x_0, x_1, x_2 WITH

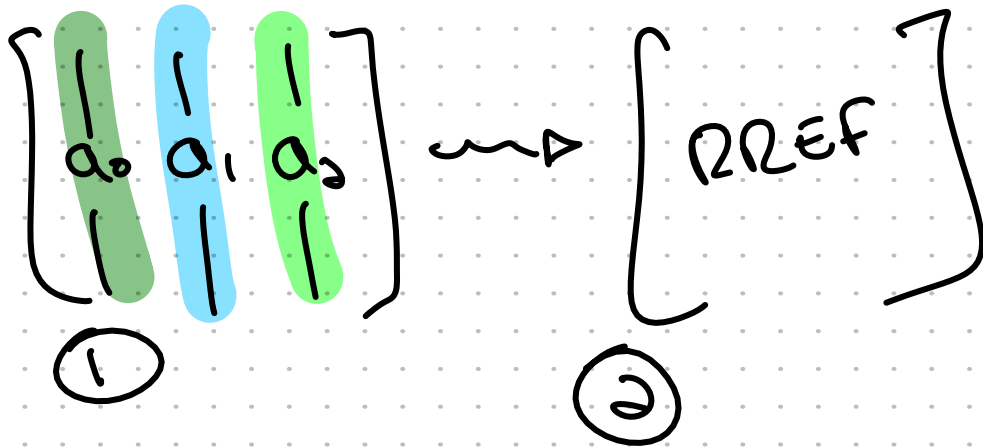
$$\vec{0} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} x_0 + \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} x_1 + \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} x_2 = \begin{bmatrix} 0 & 1 & 4 \\ 0 & 0 & 2 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 0 & 1 & 4 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & -1 & 2 & 0 \end{array} \right] \xrightarrow{\substack{r_1' = r_1 - r_0 \\ r_2' = r_2 + r_0}} \left[\begin{array}{ccc|c} 0 & 1 & 4 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & -1 & 2 & 0 \end{array} \right] \xrightarrow{\substack{r_2' = r_2 + r_1 \\ r_3' = r_3 + r_1}} \left[\begin{array}{ccc|c} 0 & 1 & 4 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

zero row \rightarrow many solutions exist \rightarrow non-zero solution exists \rightarrow linear dependence

TESTING FOR LINEAR DEPENDENCE

Are $\begin{bmatrix} 1 \\ a_0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ a_1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ a_2 \\ 1 \end{bmatrix}$ LINEARLY DEPENDENT?



1. form matrix from columns of A

2. row reduce to RREF

3. if non zero solution exists -> linear dependence

if only zero solutions exists -> linear independence

ICA 4

Determine if the following set of vectors is linearly independent

$$\begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 4 \\ 0 \\ 8 \end{bmatrix} \quad \begin{bmatrix} 3 \\ -1 \\ 5 \end{bmatrix}$$

ZERO ROW

→ LINEAR
DEPENDENT

```
matt@matt-yoga1:~$ python3
Python 3.8.10 (default, Nov 26 2021, 20:14:08)
[GCC 9.3.0] on linux
Type "help", "copyright", "credits" or "license" for more
>>> import sympy
s>>>
>>> x = sympy.Matrix([[1, 4, 3], [-2, 0, -1], [0, 8, 5]])
>>> x
Matrix([
[ 1, 4, 3],
[-2, 0, -1],
[ 0, 8, 5]])
>>> x.rref()
(Matrix([
[1, 0, 1/2],
[0, 1, 5/8],
[0, 0, 0]]), (0, 1))
>>>
```

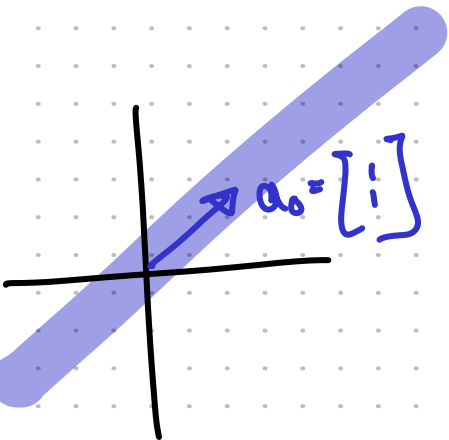
The span of N linearly independent vectors is an N dimensional space

0d space: point

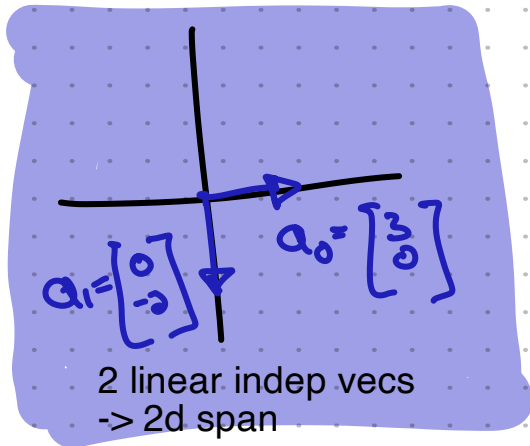
1d space: line

2d space: plane

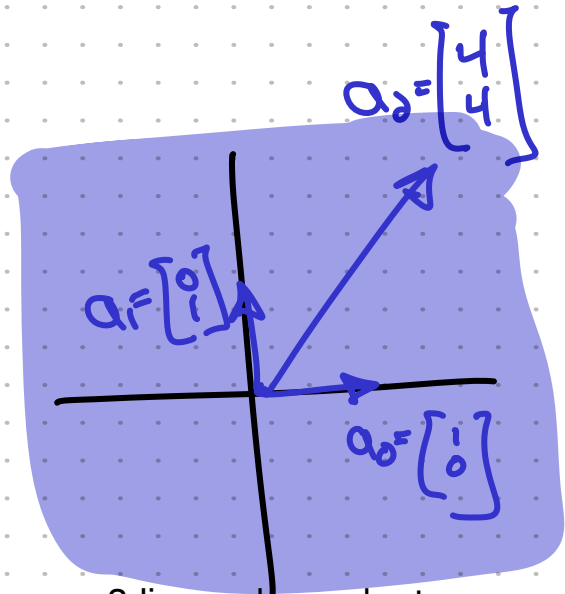
3d space: we live in a 3d space, ...



1 linear indep vec
-> 1d span



2 linear indep vecs
-> 2d span

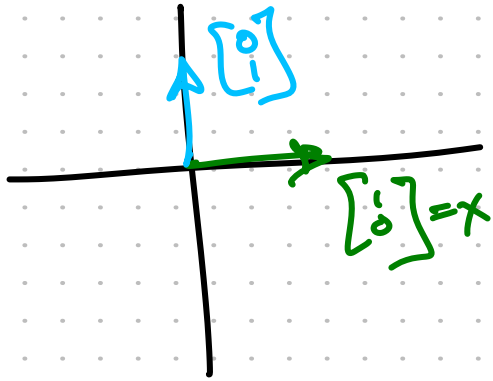


3 linear dependent vecs
-> span is not 3 dimensional

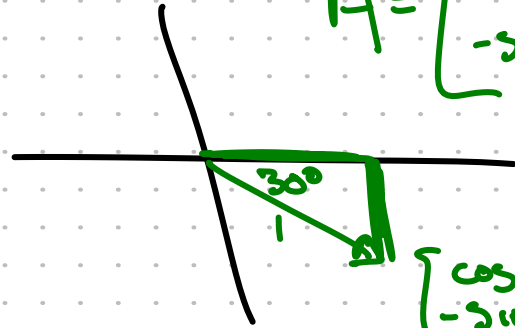
Some final, helpful facts to remember:

1. The span of N vectors is never more than an N dimensional space
2. $N+1$ or more vectors of length N are linearly dependent

A 2×2 MATRIX ROTATES 30° CLOCKWISE



Ax



$$A = \begin{bmatrix} \cos 30 & \approx \\ -\sin 30 & \approx \end{bmatrix}$$

$$\begin{bmatrix} \cos 30 \\ -\sin 30 \end{bmatrix} = Ax$$

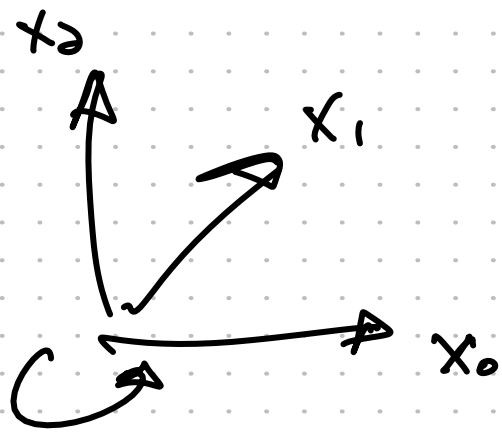
DOMAIN

$$\begin{bmatrix} \cos 30 \\ -\sin 30 \end{bmatrix} = \begin{bmatrix} | & | \\ a_0 & a_1 \\ | & | \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 1a_0 + 0a_1 = a_0$$

CODOMAIN

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 3 \\ 4 \end{bmatrix} \quad \begin{bmatrix} 5 \\ 6 \end{bmatrix}$$

3 VECTORS OF LENGTH 2
N+1



Ax

$$\begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

↙